Operating Systems Lecture 9

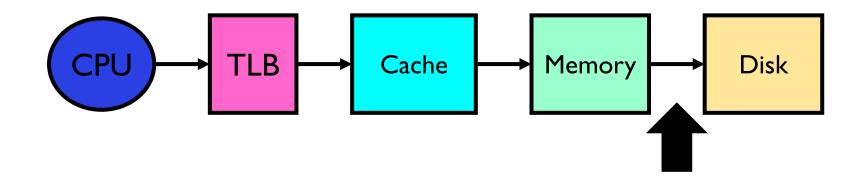
Scheduling

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Recap: Cache Hierarchy

• Memory as cache for secondary disk





Recap: Demand Paging (需求分页)

- Modern programs require a lot of physical memory, but they don't use all their memory all of the time
 - 90-10 rule: programs spend 90% of their time in 10% of their code
 - Wasteful to require all of user's code to be in memory
- Solution: use main memory as cache for disk
 - "lazy" memory allocation
- An illusion of infinite memory
 - In-use virtual memory can be bigger than physical memory
 - Combined memory of running processes much larger than physical memory
 More programs fit into memory, allowing more concurrency
 - Principle: page table for transparent management



Recap: Demand Paging as Cache

- What is block size?
 - I page
- What is organization of this cache (i.e. direct-mapped, set-associative, fully-associative)?
 - Fully associative: arbitrary virtual \rightarrow physical mapping
- How do we find a page in the cache when look for it?
 - First check TLB, then page-table traversal
- What is page replacement policy? (i.e. LRU, Random...)
 - This requires more explanation... (kinda LRU)
- What happens on a miss?
 - Go to lower level to fill miss (i.e. disk)
- What happens on a write? (write-through, write back)
 - Write-back need dirty bit!

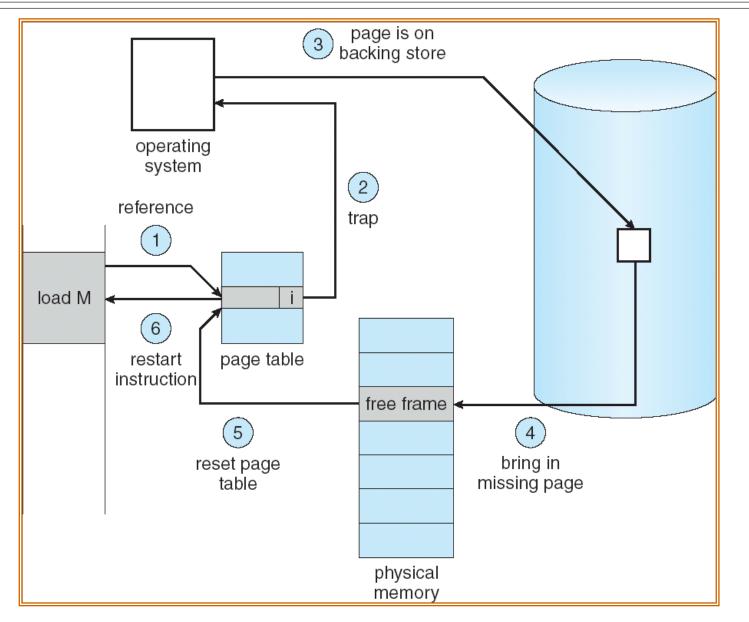


Recap: Implementation of mmap

- When program accesses an invalid address
 - I. [MMU] TLB miss; full page table lookup
 - 2. [MMU + OS] Trapping into page fault handler
 - 3. [OS] Convert virtual address to file offset
 - 4. [OS] Allocate a new page frame in memory
 - 5. [OS] Read data from disk to the memory (blocked)
 - 6. [CPU] Disk interrupt when read completes
 - 7. [OS] Updating page table by marking the entry as valid
 - 8. [OS] Resume process
 - 9. [MMU] TLB miss; full page table lookup

IO. [MMU] TLB update

Recap: Implementation of mmap

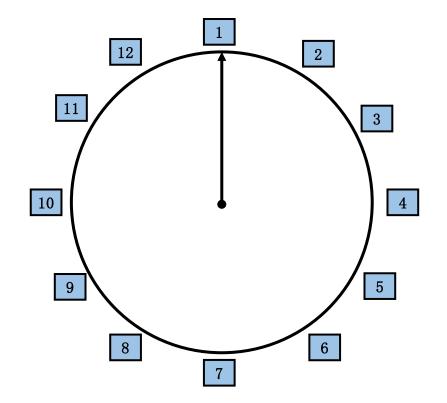




Recap: Page Eviction Policy

- Clocking algorithm: approximating LRU
- Implementation with the <u>use</u> bit
 - Initialized to 0 in page table
 - Set to I whenever there is a page access
- When we need to evict a page, we look at the page under the hand:
 - If its use bit = I, clear it and move the hand, repeat;
 - If its use bit = 0, evict it





Page reference stream:

Recap: Nth Chance Version of Clock Algorithm



- Nth chance algorithm: Give page N chances
 - OS keeps counter per page: # sweeps
 - On page fault, OS checks use bit:
 - \Box $| \rightarrow$ clear use and also clear counter (used in last sweep)
 - \Box 0 \rightarrow increment counter; if count=N, replace page
 - Means that clock hand has to sweep by N times without page being used before page is replaced
- How do we pick N?
 - Why pick large N? Better approximation to LRU
 - \Box If N ~ 1K, really good approximation
 - Why pick small N? More efficient
 - Otherwise might have to look a long way to find free page
- What about dirty pages?
 - Takes extra overhead to replace a dirty page, so give dirty pages an extra chance before replacing?
 - Common approach:
 - Clean pages, use N=1
 - \Box Dirty pages, use N=2 (and write back to disk when N=1)



Recap: Details of Clock Algorithms

- Which bits of a PTE entry are useful to us?
 - Use: Set when page is referenced; cleared by clock algorithm
 - Modified: set when page is modified, cleared when page written to disk
 - Valid: ok for program to reference this page
 - Read-only: ok for program to read page, but not modify
 For example for catching modifications to code pages!
- Do we really need hardware-supported "modified" bit?
 - No. Can emulate it (BSD Unix) using read-only bit
 - □ Initially, mark all pages as read-only, even data pages
 - □ On write, trap to OS. OS sets software ''modified'' bit, and marks page as read-write.
 - U Whenever page comes back in from disk, mark read-only



Scheduling (调度) Concept

- Why we need scheduling? Multitasks and Concurrency.
- Scheduling is only useful when there is not enough resources
- Preemption (抢占) is the basic assumption for fine-grained scheduling
 - Either by timer interrupts or other kinds of interrupts
- Who schedules processes/threads?
 - Mostly by OS.
 - User-level thread libraries schedule the threads by themselves.



Scheduling Policy Goals (1/3)

- Minimize Response Time
 - Minimize elapsed time to do an operation (or job)
 - Response time is what the user sees:
 - Time to echo a keystroke in editor
 - Time to compile a program
 - Real-time tasks: Must meet deadlines imposed by World



Scheduling Policy Goals (2/3)

- Minimize Response Time
- Maximize Throughput
 - Maximize operations (or jobs) per second
 - Throughput related to response time, but not identical:
 - Minimizing response time will lead to more context switching than if you only maximized throughput
 - Two parts to maximizing throughput
 - □ Minimize overhead (for example, context-switching)
 - Efficient use of resources (CPU, disk, memory, etc)



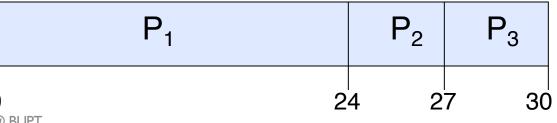
Scheduling Policy Goals (3/3)

- Minimize Response Time
- Maximize Throughput
- Fairness
 - Share CPU among users in some equitable way
 - Fairness is not minimizing average response time:
 - Better average response time by making system less fair

First-Come, First-Served (FCFS) Scheduling



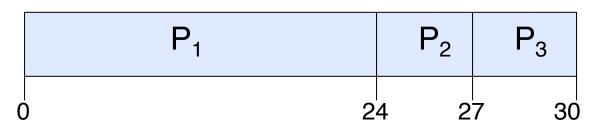
- First-Come, First-Served (FCFS, 先到先服务)
 - Also ''First In, First Out'' (FIFO, 先进先出) or ''Run until done''
 - □ In early systems, FCFS meant one program scheduled until done
 - □ Now, means keep CPU until thread blocks
- Example: Process Burst Time P_1 24 P_2 3 P_3 3
 - Suppose processes arrive in the order: P_1 , P_2 , P_3 The Gantt Chart (甘特图) for the schedule is:



First-Come, First-Served (FCFS) Scheduling



• Example continued:



- Waiting time for $P_1 = 0; P_2 = 24; P_3 = 27$
- Average waiting time: (0 + 24 + 27)/3 = 17
- Average Completion time: (24 + 27 + 30)/3 = 27
- Convoy effect (护航效应): short process behind long process

First-Come, First-Served (FCFS) Scheduling



- Example continued:
 - Suppose that processes arrive in order: P_2 , P_3 , P_1 Now, we have:



- Waiting time for $P_1 = 6; P_2 = 0; P_3 = 3$
- Average waiting time: (6 + 0 + 3)/3 = 3
- Average Completion time: (3 + 6 + 30)/3 = 13
- In second case:
 - Average waiting time is much better (before it was 17)
 - Average completion time is better (before it was 27)
- FIFO Pros and Cons:
 - Simple (+)
 - Short jobs get stuck behind long ones (-)
 Safeway: Getting milk, always stuck behind cart full of small items



Shortest Job First (SJF) Scheduling

- Shortest Job First (短任务优先) Scheduling
 - Always schedule the job with the shortest <u>remaining</u> time (so sometimes it's also called shortest-remaining-time-first, SRTF)
 - It theoretically minimizes the average response time, why?

	P ₂	P ₃	P ₁
[C) (3 6	6 30



Shortest Job First (SJF) Scheduling

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 - Always schedule the job with the shortest <u>remaining</u> time (so sometimes it's also called shortest-remaining-time-first, SRTF)
 - It theoretically minimizes the average response time, why?
- Comparison of SRTF with FCFS
 - What if all jobs the same length?
 - □ SRTF becomes the same as FCFS (i.e. FCFS is best can do if all jobs the same length)
 - What if jobs have varying length?
 - □ SRTF: short jobs not stuck behind long ones



Shortest Job First (SJF) Scheduling

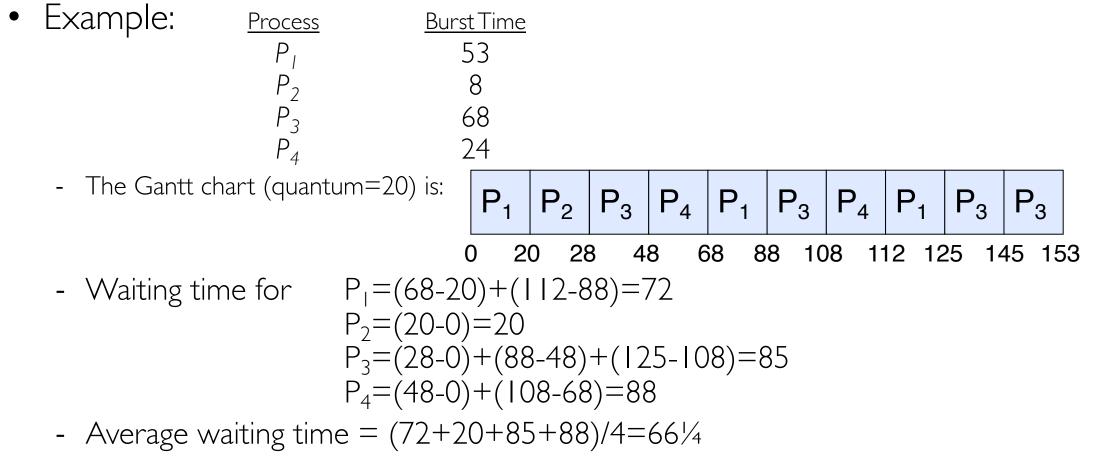
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 - Always schedule the job with the shortest <u>remaining</u> time (so sometimes it's also called shortest-remaining-time-first, SRTF)
 - It theoretically minimizes the average response time, why?
- Con#I: starvation (饥饿)
 - If small jobs keep coming, the long jobs will not be served
 - Fairness issue
- Con#2: implementation
 - It's hard to know the task remaining time



- Round Robin (轮询调度) Scheme
 - Each process gets a small unit of CPU time (*time quantum*), usually 10-100 milliseconds
 - After quantum expires, the process is preempted and added to the end of the ready queue.
- *n* processes in ready queue and time quantum is $q \Rightarrow$
 - \Box Each process gets I/n of the CPU time
 - \Box In chunks of at most *q* time units
 - \Box No process waits more than (n-1)q time units



- Example: Process Burst Time P_1 53 P_2 8 P_3 68 P_4 24
 - quantum=20
 - Average waiting time?
 - Average completion time?



- Average completion time = $(125+28+153+112)/4 = 104\frac{1}{2}$



- Thus, Round-Robin Pros and Cons:
 - Better for short jobs, Fair (+)
 - Context-switching time adds up for long jobs (-)



- Thus, Round-Robin Pros and Cons:
 - Better for short jobs, Fair (+)
 - Context-switching time adds up for long jobs (-)
- How do you choose time slice?
 - Too large: Response time suffers
 ❑ What if infinite (∞)? Falls back to FIFO
 - Too small: Throughput suffers



- Thus, Round-Robin Pros and Cons:
 - Better for short jobs, Fair (+)
 - Context-switching time adds up for long jobs (-)
- How do you choose time slice?
- Actual choices of timeslice:
 - Initially, UNIX timeslice one second:
 - Worked ok when UNIX was used by one or two people.
 - □ What if three compilations going on? 3 seconds to echo each keystroke!
 - Need to balance short-job performance and long-job throughput:
 Typical time slice today is between 10ms 100ms
 Typical context-switching overhead is 0.1ms 1ms
 - □ Roughly 1% overhead due to context-switching



Comparing FCFS and RR

- Assuming zero-cost context-switching time, is RR always better than FCFS?
- Simple example:

- 10 jobs, each take 100s of CPU time RR scheduler quantum of 1s All jobs start at the same time
- Completion Times:

Job #	FIFO	RR		
I	100	991		
2	200	992		
•••	•••			
9	900	999		
10	1000	1000		

- Average response time

□ Bad when all jobs same length

- Also: Cache state must be shared between all jobs with RR but can be devoted to each job with FIFO
 - Total time for RR longer even for zero-cost switch!

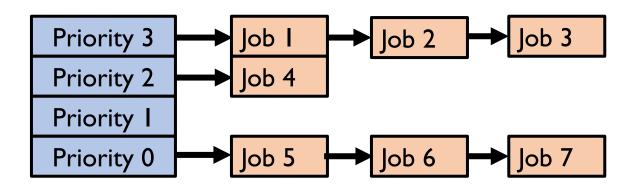


Choice of Time Quantum for RR

Best FCFS:	P ₂ P ₄ [8] [24]	P ₁ [53]		P ₃ [68]		
	0 8	32	8.	5	I	53
	Quantum	P _I	P ₂	P ₃	P ₄	Average
	Best FCFS	32	0	85	8	311/4
	Q = 1	84	22	85	57	62
Wait	Q = 5	82	20	85	58	611/4
Time	Q = 8	80	8	85	56	57¼
Time	Q = 10	82	10	85	68	611/4
	Q = 20	72	20	85	88	66 ¹ /4
	Worst FCFS	68	145	0	121	831/2
	Best FCFS	85	8	153	32	69 ¹ / ₂
	Q = 1	137	30	153	81	1001/2
Completion	Q = 5	135	28	153	82	99 ¹ / ₂
Completion Time	Q = 8	133	16	153	80	95 ½
	Q = 10	135	18	153	92	99 ¹ / ₂
	Q = 20	125	28	153	112	1041/2
	Worst FCFS	121	153	68	145	121¾



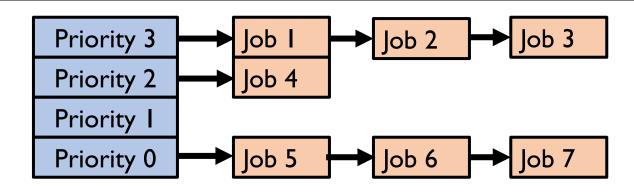
Strict Priority Scheduling



- Strict Priority Scheduling (严格优先级调度)
 - Always execute highest-priority runnable jobs to completion
 - Each queue can be processed in RR with some time-quantum
- Problems:
 - Starvation: Lower priority jobs don't get to run because higher priority jobs
 - Deadlock: Priority Inversion (优先级翻转)
 - Not strictly a problem with priority scheduling, but happens when low priority task has lock needed by high-priority task



Strict Priority Scheduling

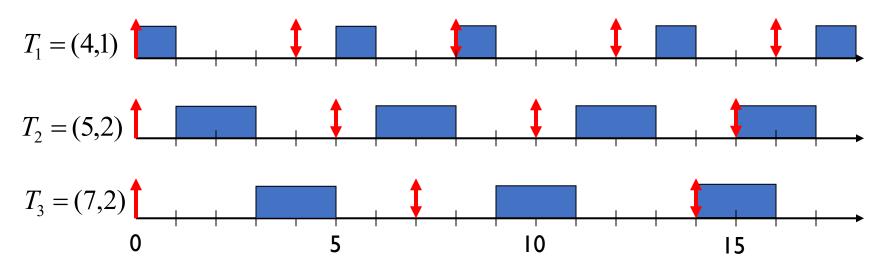


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 - Deadlock: Priority Inversion (优先级翻转)
- How to fix? Dynamic priority
 - Dynamic priorities adjust base-level priority up or down based on heuristics about interactivity, locking, burst behavior, etc...



Earliest Deadline First (EDF)

- Tasks periodic with period P and computation C in each period: (P, C)
- Preemptive priority-based dynamic scheduling
- Each task is assigned a (current) priority based on how close the absolute deadline is
- The scheduler always schedules the active task with the closest absolute deadline



Scheduling Fairness



- What about fairness?
 - Strict fixed-priority scheduling between queues is unfair (run highest, then next, etc):
 - Long running jobs may never get CPU
 - □ In Multics, shut down machine, found 10-year-old job
 - Must give long-running jobs a fraction of the CPU even when there are shorter jobs to run
 - Tradeoff: fairness gained by hurting avg response time!



- How to implement fairness?
 - Could give each queue some fraction of the CPU
 - □ What if one long-running job and 100 short-running ones?
 - Like express lanes in a supermarket—sometimes express lanes get so long, get better service by going into one of the other lines
 - Could increase priority of jobs that don't get service
 - $\hfill\square$ What is done in some variants of UNIX
 - □ This is ad hoc—what rate should you increase priorities?
 - □ And, as system gets overloaded, no job gets CPU time, so everyone increases in priority⇒Interactive jobs suffer

Scheduling Fairness



- If every tasks need the same resource, fairness is easy: RR.
- Yet, tasks may demand different: compute-bound vs. I/O bound
- Max-Min fairness: iteratively maximize the minimum allocation given to a particular process (or threads/users/applications) until all resources are assigned
 - Mostly used in network

Multi-level Feedback Queue (MFQ) Scheduling



- Multi-level Feedback Queue (MFQ, 多级反馈队列调度)
 - Achieves responsiveness (short jobs quickly as SJF), low overhead (minimizing the preemptions and scheduling decision time), and starvation-free (as RR), and fairness (approximately max-min fair share).

Yet, it does not perfectly achieve any of these goals.

- Widely used in commercial OSes such as Windows, MacOS, and Linux.
- Assuming a mix of two kinds of workloads
 - 1 Interactive tasks (e.g., waiting for user keyboard input): using CPU for a short time, then yield for I/O waiting. Low latency is critical.
 - (2) CPU-intensive tasks (e.g., compressing files): using CPU for a long period of time. The response time often does not matter much.

Multi-level Feedback Queue (MFQ) Scheduling



- A naïve version of MFQ: maintaining many tasks queues with different priorities, and use following schedule rules.
 - Rule I: If Priority(A) > Priority(B), A runs (B doesn't).
 - Rule 2: If Priority(A) = Priority(B), A & B run in RR.
- The key here is how to set the priority.
 - Intuitively, if a job repeatedly relinquishes the CPU while waiting for input from the keyboard, it shall be kept in high priority.
 - Otherwise, if a job uses CPU intensively for long periods of time, its priority shall be reduced.

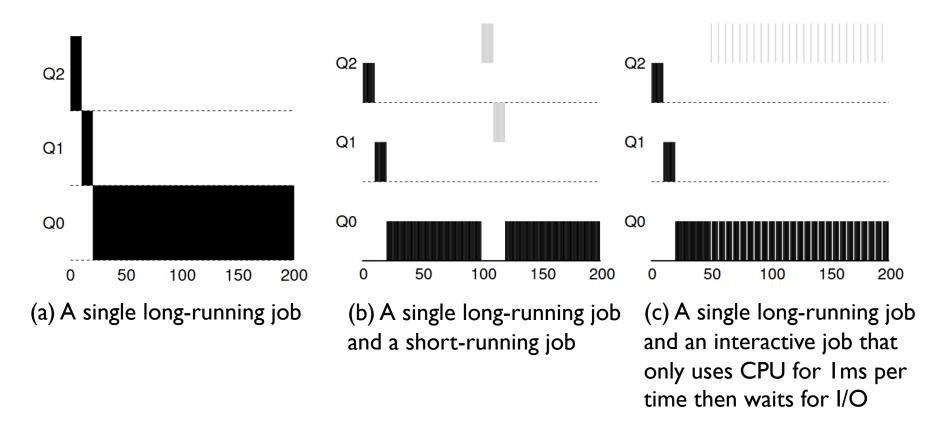
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 - Rule I: If Priority(A) > Priority(B), A runs (B doesn't).
 - Rule 2: If Priority(A) = Priority(B), A & B run in RR.
- Our solution: assign a quota for each job at a given priority level, and reduces its priority once the quota is used up.
 - Rule 3: When a job enters the system, it is placed at the highestpriority (the topmost queue).
 - Rule 4a: If a job uses up its allotment while running, its priority isreduced (i.e., it moves down one queue).
 - Rule 4b: If a job gives up the CPU (for example, by performing an I/O operation) before the allotment is up, it stays at the samepriority level (i.e., its allotment is reset).



• A few illustrative examples of our naïve MFQ design.

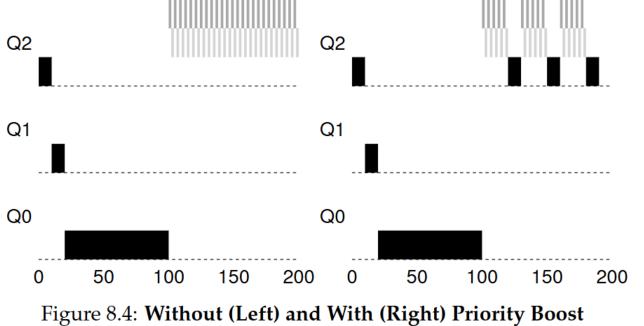




- There are many issues with this naïve version of MFQ.
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- Solution#I: priority boost
 - Rule 5: After some time period S, move all the jobs in the system to the topmost queue.
 - S shall be neither too large or too small. Why?



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- Solution#I: priority boost
 - Rule 5: After some time period S, move all the jobs in the system to the topmost queue.
 - S shall be neither too large or too small. Why?
- Solution#2: time slice across queues
 - each queue gets a certain amount of CPU time
 - e.g., 70% to highest, 20% next, 10% lowest
- More solutions..



- There are many issues with this naïve version of MFQ.
 - Starvation: if there are ''too many'' interactive jobs in the system, they will consume all CPU time, and thus long-running jobs will starve.
 - Countermeasure: user action that can foil intent of OS designers, e.g., put in a bunch of meaningless I/O to keep job's priority high.
 - How to parameterize the scheduler: how many queues should there be? How big should the time slice be per queue?
 - More..
- Think of possible solutions to them?



- To further extend the MFQ design: Each queue has its own scheduling parameters or even different algorithms!
 - e.g. foreground RR, background FCFS
 - □ Sometimes multiple RR priorities with quantum increasing exponentially (highest: I ms, next: 2ms, next: 4ms, etc)
- Adjust each job's priority as follows (details vary)
 - Job starts in highest priority queue
 - If timeout expires, drop one level
 - If timeout doesn't expire, push up one level (or stay at the same one)

- A test
- Assume we have 4 processes in a system with multilevel feedback queue scheduling policy. All the processers arrived ate time 0 and located in the highest level queue in the order of their IDs (1 to 4) a) Calculate the average waiting time and average turnaround time.

<u>Process</u>	Burst Time	quantum = 8
P_1	11	
P_2	26	quantum = 16
P ₃	31	
P_4	45	FCFS FCFS

b) If a new process P_5 enters the system at time 35 how the gantt chart is going to change?



Fair-share Scheduler

- This type of scheduler aims to guarantee that each job obtain a certain percentage of CPU time.
 - Also known as "proportional-share scheduler.
- Next, we will discuss two types of fair-share scheduler.
 - Lottery scheduling
 - The Linux Completely Fair Scheduler (CFS)



- Lottery Scheduling
 - Give each job some number of lottery tickets
 - On each time slice, randomly pick a winning ticket
 - On average, CPU time is proportional to number of tickets given to each job (but not deterministically!)
- Assuming there are two jobs: A with 75 tickets, B with 25 tickets
 - Here, B gets run 4 out of 20 time slices (20%).
 - With more tries, B is more likely to get 25% slices.

```
      Here is an example output of a lottery scheduler's winning tickets:

      63
      85
      70
      39
      76
      17
      29
      41
      36
      39
      10
      99
      68
      83
      63
      62
      43
      0
      49
      12

      Here is the resulting schedule:

      A
      A
      A
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```



- Lottery Scheduling
 - Give each job some number of lottery tickets
 - On each time slice, randomly pick a winning ticket
 - On average, CPU time is proportional to number of tickets given to each job
- How to assign tickets?
 - To approximate SRTF, short running jobs get more, long running jobs get fewer
 - To avoid starvation, every job gets at least one ticket (everyone makes progress)
- Advantage over strict priority scheduling: behaves gracefully as load changes
 - Adding or deleting a job affects all jobs proportionally, independent of how many tickets each job possesses



- Lottery Scheduling Example
 - Assume short jobs get 10 tickets, long jobs get 1 ticket

# short jobs/ # long jobs	% of CPU each short jobs gets	% of CPU each long jobs gets	
1/1	??	??	
0/2	??	??	
2/0	??	??	
10/1	??	??	
1/10	??	??	



- Lottery Scheduling Example
 - Assume short jobs get 10 tickets, long jobs get 1 ticket

# short jobs/ # long jobs	% of CPU each short jobs gets	% of CPU each long jobs gets	
1/1	91%	9%	
0/2	N/A	50%	
2/0	50%	N/A	
10/1	9.9%	0.99%	
1/10	50%	5%	

Lottery Scheduling



- Implementing lottery scheduling is amazingly easy!
 - One of the important feature of it.
- You only need
 - I. A good random number generator
 - 2. A data structure to track the processes of the system and the total number of tickets

Lottery Scheduling



```
Job:B
                  Job:A
                                         Job:C
                                                   NULL
       head
                  Tix:100
                             Tix:50
                                        Tix:250
   // counter: used to track if we've found the winner yet
1
   int counter = 0;
2
3
   // winner: call some random number generator to
4
  // get a value >= 0 and <= (totaltickets - 1)</pre>
5
   int winner = getrandom(0, totaltickets);
6
7
   // current: use this to walk through the list of jobs
8
   node_t *current = head;
9
   while (current) {
10
       counter = counter + current->tickets;
                                                          An optimization:
11
       if (counter > winner)
12
                                                          organize the list
           break; // found the winner
13
                                                          in sorted order
       current = current->next;
14
15
      'current' is the winner: schedule it...
16
```

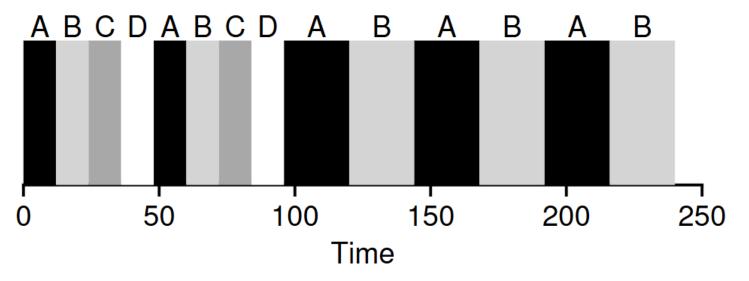


- The default Linux scheduler since v2.6.23 (2007).
 - The goal of **CFS**: to fairly divide a CPU evenly among all competing processes.
- CFS uses a counting-based technique known as virtual runtime (vruntime)
 - As each process runs, it accumulates <mark>vruntime</mark>, e.g., in proportion with the physical (real) time.
 - When a scheduling decision occurs, CFS will pick the process with the lowest vruntime to run next.
- How does CFS know when to stop the running process?
 - The scheduling time slice. Either too large or small. Why?



Completely Fair Scheduler (CFS)

- CFS decides the scheduling interval based on the number of currently running processes.
 - sched_latency divided by the number of processes
 why?
 - E.g., 48 milliseconds / 4 processes = 12 milliseconds
 - What if there are too many processes? Set a minimal value of time slice: <u>min_granularity</u>.





- CFS also enables controls over process priority, enabling users to give some processes a higher share of the CPU.
 - Using a UNIX mechanism known as the nice level of a process.
 - Larger nice, lower priority.

static const int prio_to_weight[40] = { */*★ *-*20 ★*/* 88761, 71755, 56483, 46273, 36291, /* −15 */ 29154, 23254, 18705, 14949, 11916, */*★ −10 ★*/* 9548, 7620, 6100, 4904, 3906, /* -5 */ 3121, 2501, 1991, 1586, 1277, /* 0 */ 1024, 820, 655, 526, 423, /* 5 */ 335, 272, 215, 172, 137, /* 10 */ 110, 87, 70, 56, 45, /* 15 */ 36, 29, 23, 18, 15,

Two jobs: A with nice value of -5, B with nice value of 0. sched latency is 48ms. What is the time slice of A and B?

};

$$\texttt{time_slice}_k = \frac{\texttt{weight}_k}{\sum_{i=0}^{n-1}\texttt{weight}_i} \cdot \texttt{sched_latency}$$



$\texttt{vruntime}_i = \texttt{vruntime}_i + \frac{\texttt{weight}_0}{\texttt{weight}_i} \cdot \texttt{runtime}_i$

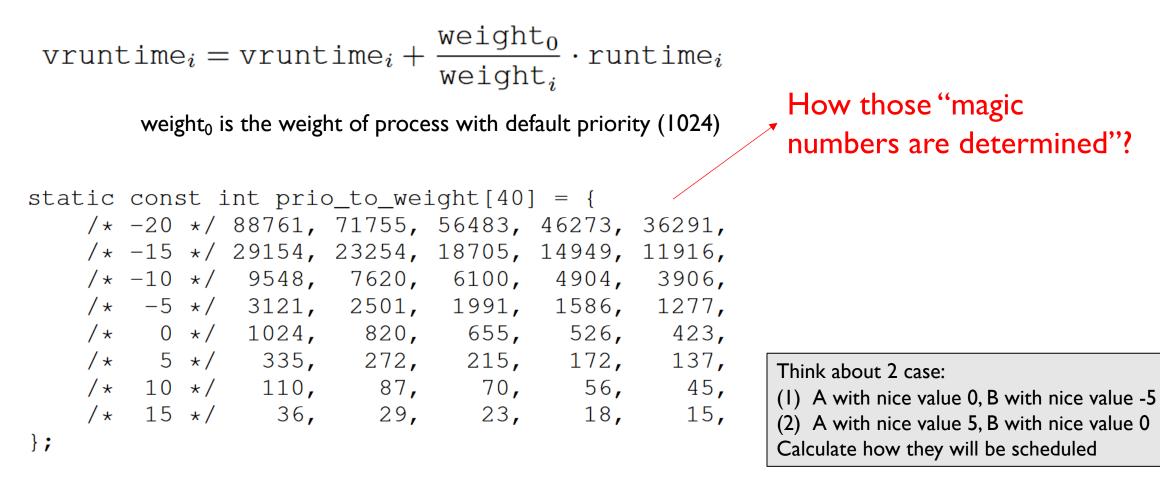
weight₀ is the weight of process with default priority (1024)

<pre>static const int prio_to_weight[40] = {</pre>							
/*	-20	*/	88761,	71755,	56483,	46273,	36291,
/*	-15	*/	29154,	23254,	18705,	14949,	11916 ,
/*	-10	*/	9548,	7620,	6100,	4904,	3906,
/*	-5	*/	3121,	2501,	1991,	1586,	1277,
/*	0	*/	1024,	820,	655,	526,	423,
/*	5	*/	335,	272,	215,	172,	137,
/*	10	*/	110,	87,	70,	56,	45,
/*	15	*/	36,	29,	23,	18,	15,
};							

$$\texttt{time_slice}_k = \frac{\texttt{weight}_k}{\sum_{i=0}^{n-1}\texttt{weight}_i} \cdot \texttt{sched_latency}$$







$$\texttt{time_slice}_k = \frac{\texttt{weight}_k}{\sum_{i=0}^{n-1}\texttt{weight}_i} \cdot \texttt{sched_latency}$$



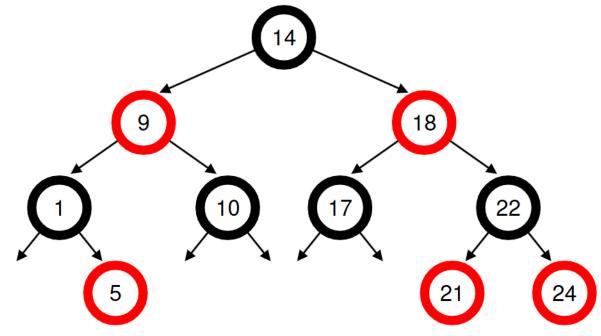
Completely Fair Scheduler (CFS)

- Implementing CFS
 - The ops to be supported: (1) finding the process with lowest <mark>vruntime</mark>; (2) insert/delete a process
- Approach#1: Ordered List
 - Finding the next job: O(1)
 - Insert/delete: O(n)



Completely Fair Scheduler (CFS)

- Implementing CFS
 - The ops to be supported: (1) finding the process with lowest vruntime; (2) insert/delete a process
- Approach#1: Ordered List
 - Finding the next job: O(I)
 - Insert/delete: O(n)
- Approach#2: Red-Black Tree
 - Finding the next job: O(log n)
 - Insert/delete: O(log n)
 A node is either red or black
 - The root is black
 - □All leaves (NULL) are black
 - ■Both children of every red node are black
 - \Box Every simple path from root to leaves contains the same number of black nodes.



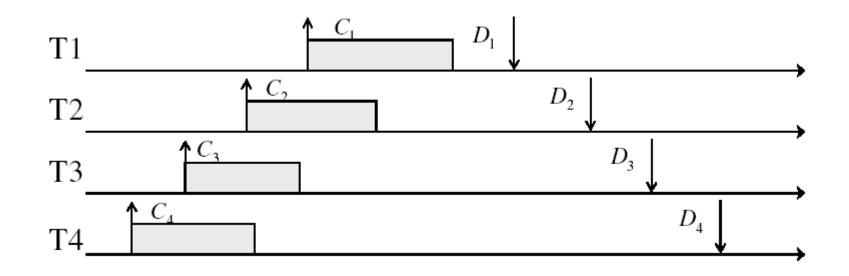


- Efficiency is important but predictability is essential:
 - We need to predict with confidence worst case response times for systems
 - In RTS, performance guarantees are:
 - Task- and/or class centric and often ensured a priori
 - In conventional systems, performance is:
 - System/throughput oriented with post-processing (... wait and see ...)
 - Real-time is about enforcing predictability, and does not equal fast computing!!!
- Hard Real-Time
 - Attempt to meet all deadlines
 - EDF (Earliest Deadline First), LLF (Least Laxity First), RMS (Rate-Monotonic Scheduling), DM (Deadline Monotonic Scheduling)
- Soft Real-Time
 - Attempt to meet deadlines with high probability
 - Minimize miss ratio / maximize completion ratio (firm real-time)
 - Important for multimedia applications
 - CBS (Constant Bandwidth Server)



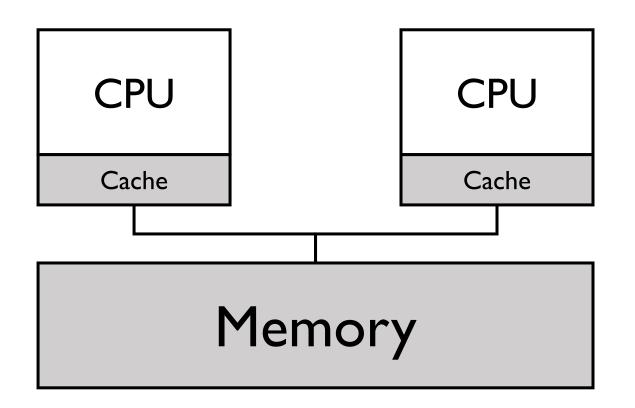
Real-Time Scheduling (RTS)

- Tasks are preemptable, independent with arbitrary arrival (=release) times
- Tasks have deadlines (D) and known computation times (C)
- Example Setup:



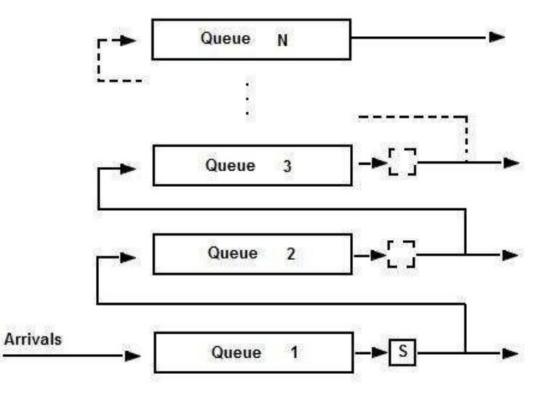


• Recall: the cache-memory system, and cache consistency (or coherency) (缓存一致性)



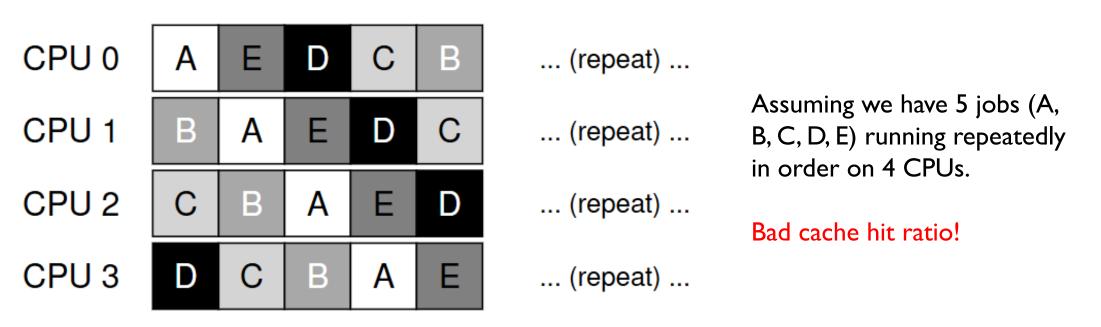


• What's wrong with a centralized MFQ?





- What's wrong with a centralized MFQ?
 - Contention for the MFQ lock
 - The lock could become a bottleneck especially with large number of processors
 - Cache coherence overhead
 - The MFQ data structure will be modified often and cause cache miss when a processor gets its lock to use MFQ





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 - The MFQ data structure will be modified often and cause cache miss when a processor gets its lock to use MFQ
 - Limited cache reuse
 - A thread is likely to be scheduled on different processors, so the L1 cache needs to be fetched from the memory again



- What's wrong with a centralized MFQ?
 - Contention for the MFQ lock
 - Cache coherence overhead
 - Limited cache reuse
- Modern OSes use per-processor MFQ
- Affinity scheduling (亲和性调度): a thread is always (re)scheduled to the same processor
 - Rebalancing across processors only happens when necessary

How to Evaluate a Scheduling algorithm?



- Deterministic modeling
 - Takes a predetermined workload and compute the performance of each algorithm for that workload
- Queueing models (排队论/模型)
 - Mathematical approach for handling stochastic workloads
 - Commonly used in a variety of fields, including computer science, telecommunications, operations research, and industrial engineering
- Implementation/Simulation:
 - Build system which allows actual algorithms to be run against actual data most flexible/general



Summary of Scheduling Algorithms

- Round-Robin Scheduling:
 - Give each thread a small amount of CPU time when it executes; cycle between all ready threads
 - Pros: Better for short jobs
- Shortest Job First (SJF) / Shortest Remaining Time First (SRTF):
 - Run whatever job has the least amount of computation to do/least remaining amount of computation to do
 - Pros: Optimal (average response time)
 - Cons: Hard to predict future, Unfair
- Multi-Level Feedback Scheduling:
 - Multiple queues of different priorities and scheduling algorithms
 - Automatic promotion/demotion of process priority in order to approximate SJF/SRTF



Summary of Scheduling Algorithms

- Lottery Scheduling:
 - Give each thread a priority-dependent number of tokens (short tasks \Rightarrow more tokens)
- Linux CFS
 - Completely fair across processes (always assign to the one with least running time)
 - Dynamically adjust time slice of each process
 - Using priority (nice level) to control the assignment
- Real-time scheduling
 - Need to meet a deadline, predictability essential
 - Earliest Deadline First (EDF) and Rate Monotonic (RM) scheduling



Summary of Scheduling Algorithms

- This course only covers very basic knowledge of scheduling
 - The schedulers used in real OSes are more complex
 - Choosing a proper schedule depends on many factors: hardware, workloads, etc..
 - Note: almost every hardware resource needs scheduler.
 GPU, disk, network, etc..
 - Scheduling is common in real-world life
 - Use what you learned to solve them!
 - Example #1: Hospital emergencies?
 - Example #2: Air traffic control?
 - Example #3: Supermarket checkout?
 - Example #4: Print jobs in a printer?
 - Example #5: Control system in a rocket?
 - Example #6: Engine control unit in an automotive application

Homework



• Some simple code about MLFQ. Check out our website.